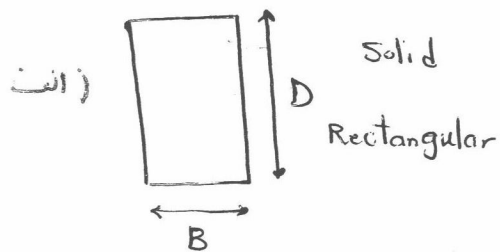


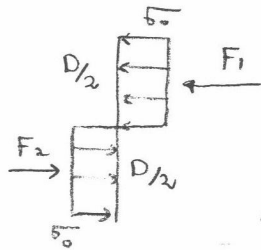
(یافتن ضرایب شکل تقاطع دلتا)

* در تقاطع زیر مطلوب است اثبات روابط Z_p و α



$$Z_p = \frac{1}{4} B D^2$$

$$\alpha = 1.50$$



گام اول: یافتن M_p

$$F_1 = F_2 = F = \frac{D}{2} \cdot b_0 \cdot B = \frac{B D b_0}{2}$$

$$M_p = 2 F \cdot \frac{D}{2} \cdot \frac{1}{2} = \frac{F D}{2} = \frac{B D^2 b_0}{4}$$

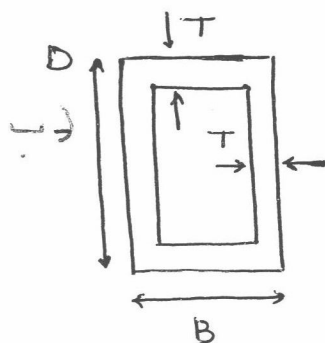
$$Z_p = \frac{M_p}{b_0} = \frac{B D^2}{4} \quad \checkmark$$

گام دوم: یافتن S_e or M_y

$$S_e = \frac{I}{\frac{D}{2}} = \frac{2I}{D} \quad \text{and} \quad I = \frac{1}{12} B D^3$$

$$S_e = \frac{2}{D} \cdot \frac{1}{12} B D^3 = \frac{B D^2}{6}$$

$$\alpha = \frac{Z_p}{S_e} = \frac{B D^2}{4} \cdot \frac{6}{B D^2} = 1.50 \quad \checkmark$$



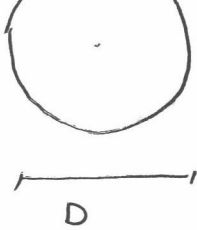
گام سوم: مقدار وکرا یا یافتن M_y و تقسیم آن بر b_0 بدست آوردن Z_p

$$Z_p = B T (D - T) + \frac{T}{2} (D - 2T)^2$$

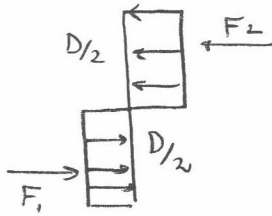
$$\text{if } B = D$$

$$\rightarrow \alpha = 1.18$$

$$T = 0.050 D$$



$$v = \frac{16}{3\pi} = 1.70$$



$$F_1 = F_2 = F = \frac{1}{2} \cdot \frac{\pi}{4} D^2 \sigma_0$$

$$= \frac{\pi D^2 \sigma_0}{8}$$

MP : (1م⁶)

محل اثر نیروها : $\frac{4r}{3\pi} = \frac{4}{3\pi} \cdot \frac{D}{2} = \frac{2D}{3\pi}$

$$M_P = 2F \cdot \frac{2D}{3\pi} = \frac{4D}{3\pi} \cdot \frac{\pi D^2 \sigma_0}{8} = \frac{D^3 \sigma_0}{6}$$

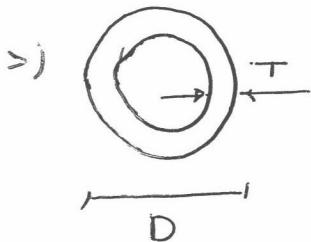
$$z_P = \frac{M_P}{\sigma_0} = \frac{D^3}{6} \quad \checkmark$$

$$S_e = \frac{\pi}{32} D^3$$

برای سطح ویریداری

Se : (2م⁶)

$$v = \frac{z_P}{S_e} = \frac{D^3}{6} \cdot \frac{32}{\pi D^3} = \frac{16}{3\pi} \quad \checkmark$$



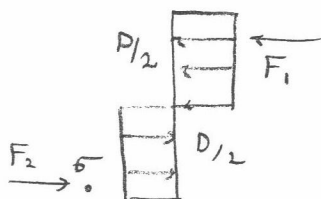
$$z_P = \frac{1}{6} D^3 \left(1 - \left(1 - \frac{2T}{D} \right)^3 \right)$$

$$T = 0.050 D$$

$$v = 1.34$$

$$T \ll D$$

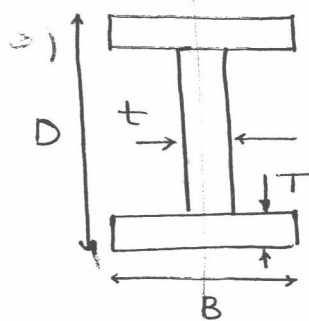
$$v = \frac{4}{\pi} = 1.27$$



$$F_1 = F_2 = \frac{1}{2} \cdot \frac{\pi}{4} (D^2 - (D-2T)^2) \sigma_0$$

$$= \frac{\pi \sigma_0}{8} (D^2 - (D-2T)^2)$$

MP : (1م⁶)

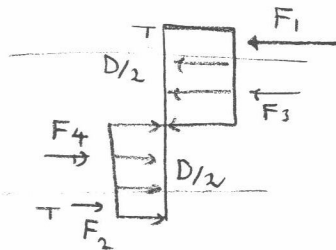


Axis X-X

$$z_P = BT \cdot (D - T) + \frac{1}{4} t (D - 2T)^2 \quad \checkmark \approx 1.14$$

Axis Y-Y

$$z_P = \frac{1}{2} TB^2 + \frac{1}{4} (D - 2T) t^2 \quad \checkmark \approx 1.60$$



$M_P = ?$: Axis X-X - الف

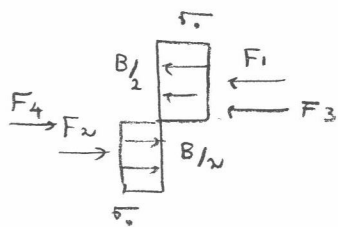
$$F_1 = F_2 = BT \cdot \bar{y}_o$$

$$F_3 = F_4 = \left(\frac{D}{2} - T\right) \cdot t \cdot \bar{y}_o = \frac{\bar{y}_o t}{2} (D - 2T)$$

$$M_P = 2 F_1 \cdot \left(\frac{D}{2} - \frac{T}{2}\right) + 2 F_3 \cdot \left(\frac{D}{2} - T\right) \cdot \frac{1}{2}$$

$$= BT \bar{y}_o (D - T) + \frac{\bar{y}_o t}{2} \cdot \frac{1}{2} (D - 2T)^2$$

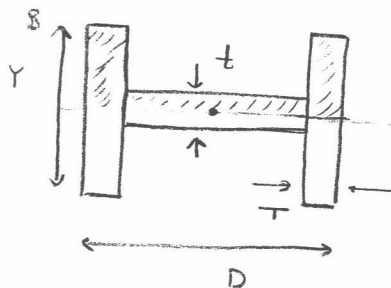
$$z_P = \frac{M_P}{\bar{y}_o} = BT \cdot (D - T) + \frac{t}{4} (D - 2T)^2 \quad \checkmark$$



$M_P = ?$: Axis Y-Y - ب

$$F_1 = F_2 = 2 \cdot \frac{B}{2} \cdot T \cdot \bar{y}_o = BT \bar{y}_o$$

$$F_3 = F_4 = (D - 2T) \cdot \frac{t}{2} \cdot \bar{y}_o = \frac{\bar{y}_o t}{2} (D - 2T)$$



$$M_{P1} = 2 F_1 \cdot \frac{B}{4} = \frac{BF_1}{2} = \frac{B^2 T \bar{y}_o}{2}$$

$$M_{P2} = 2 F_3 \cdot \frac{t}{4} = \frac{F_3 t}{2} = \frac{\bar{y}_o t^2}{4} (D - 2T)$$

$$M_P = M_{P1} + M_{P2}$$

$$z_P = \frac{M_P}{\bar{y}_o} = \frac{B^2 T}{2} + \frac{t^2}{4} (D - 2T) \quad \checkmark$$